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作者 (\*) : Chen, Mei; Zhu, Linghan Source: 2017 2ND INTERNATIONAL  
CONFERENCE ON ROBOTICS AND AUTOMATION ENGINEERING (ICRAE),  
259-263 2017 Document Type: Proceedings Paper

250. [Dynamic Load-Carrying Capacity Analysis of Space Manipulators with Joint Friction](#)

作者 (\*) : Liu Yong; Zhu Wenpei Source: 2017 2ND INTERNATIONAL  
CONFERENCE ON ROBOTICS AND AUTOMATION ENGINEERING (ICRAE),  
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